

# Corin

Connected Orthopaedic Insight

## Understanding Robotic Assisted TKA with Digital Gap Planning

Dr Amber Randall





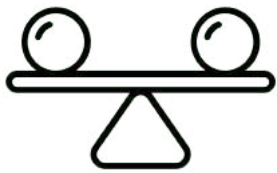
## Technology Overview

Dr John Keggi



## What Are We Aiming For?

Dr Jeffrey DeClaire



## Challenging Tradition to Optimize Stability

Dr Jeffrey Lawrence



## Data Driven Decision Making: Bringing Efficiency to the OR

Dr Amber Randall



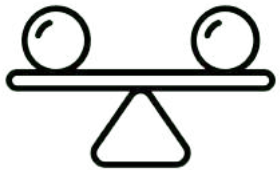
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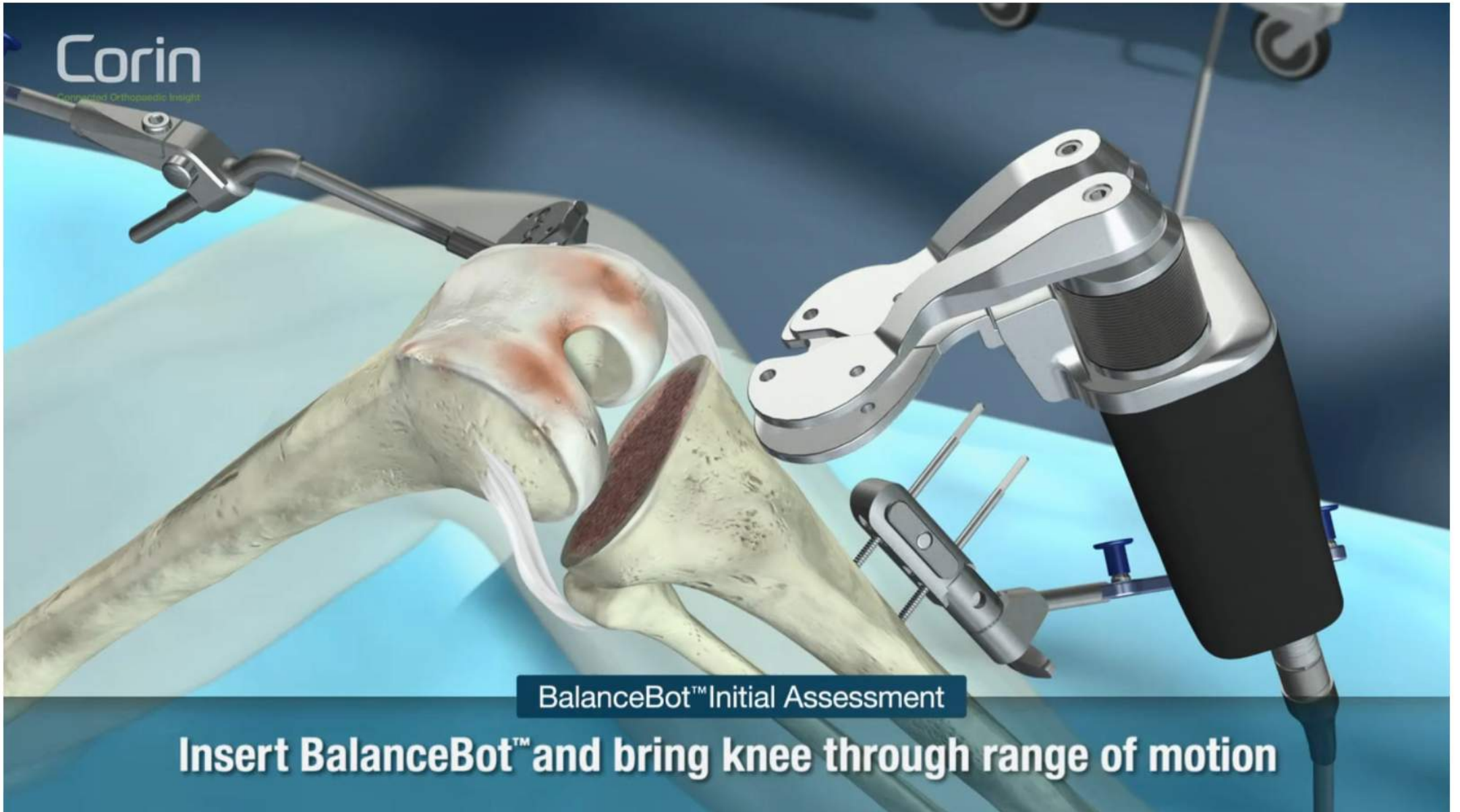
# Data Driven Decision Making

Dr Amber Randall

- Technique Recap
- Clinical Guidelines
- Corin Joint Arthroplasty Registry (JAR)
- Managing An Efficient OR

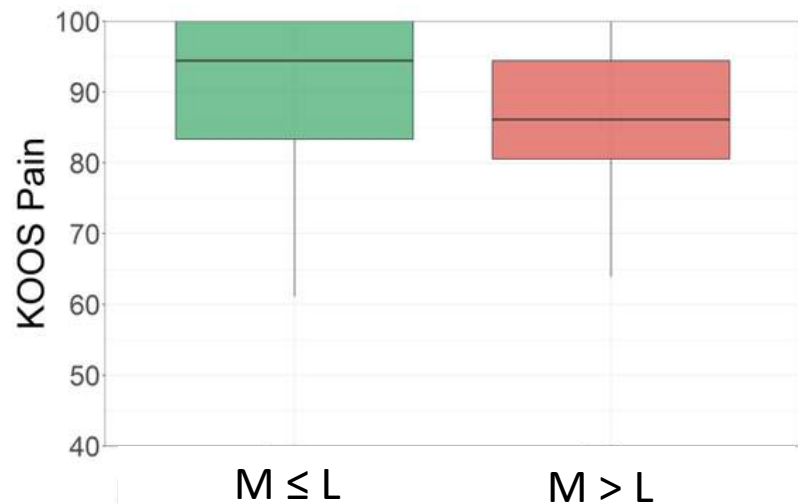
## Part 1: Technique Recap



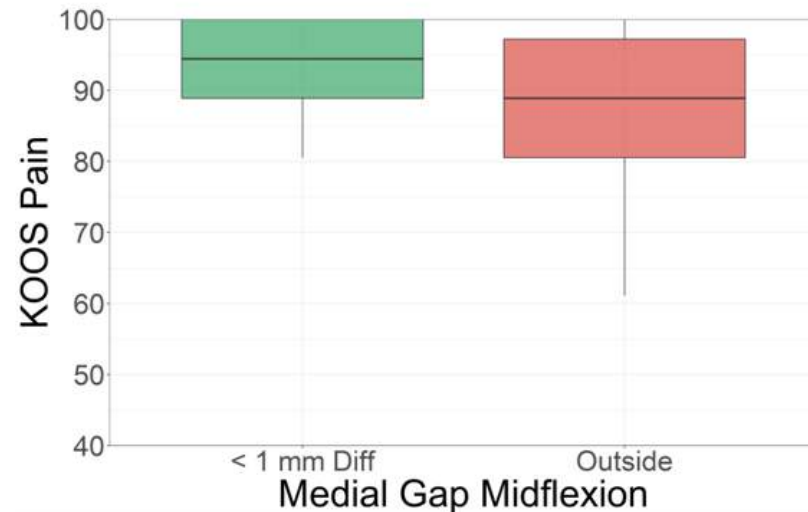


## Part 2: Clinical Guidelines

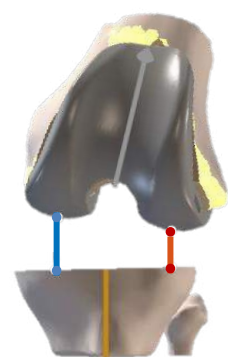
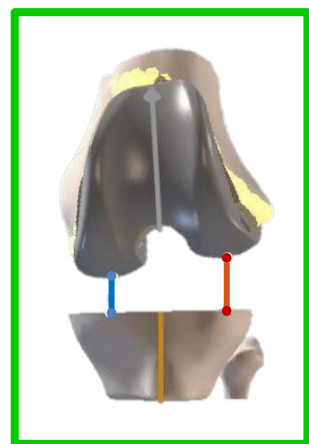
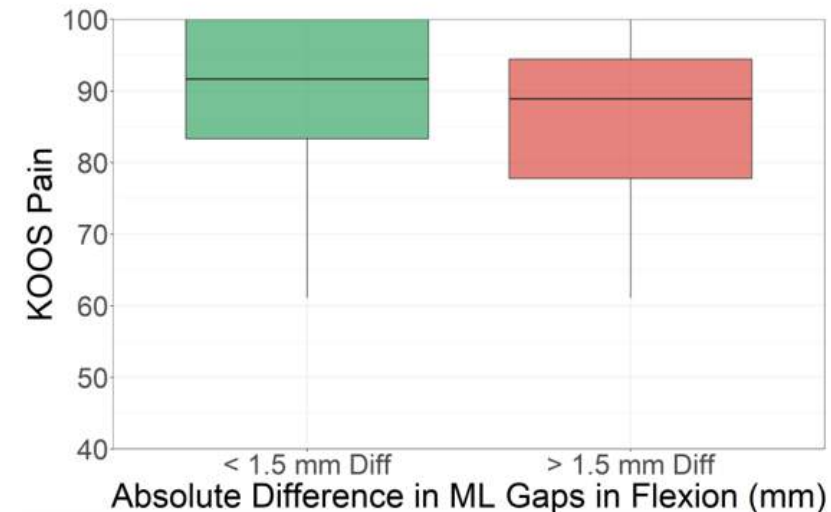
### Extension



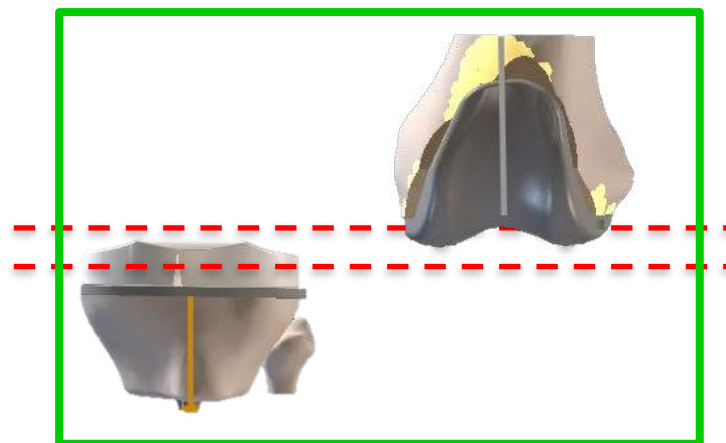
### MidFlexion



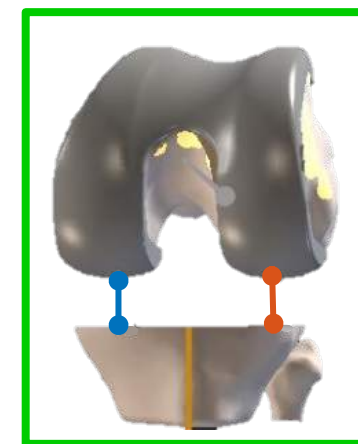
### Flexion



$\Delta 8.3, p = 0.007$



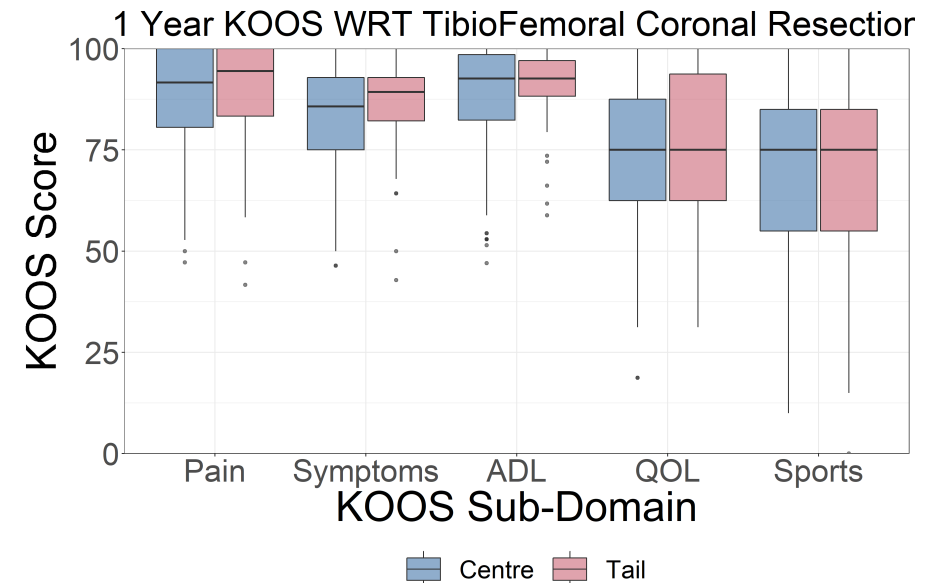
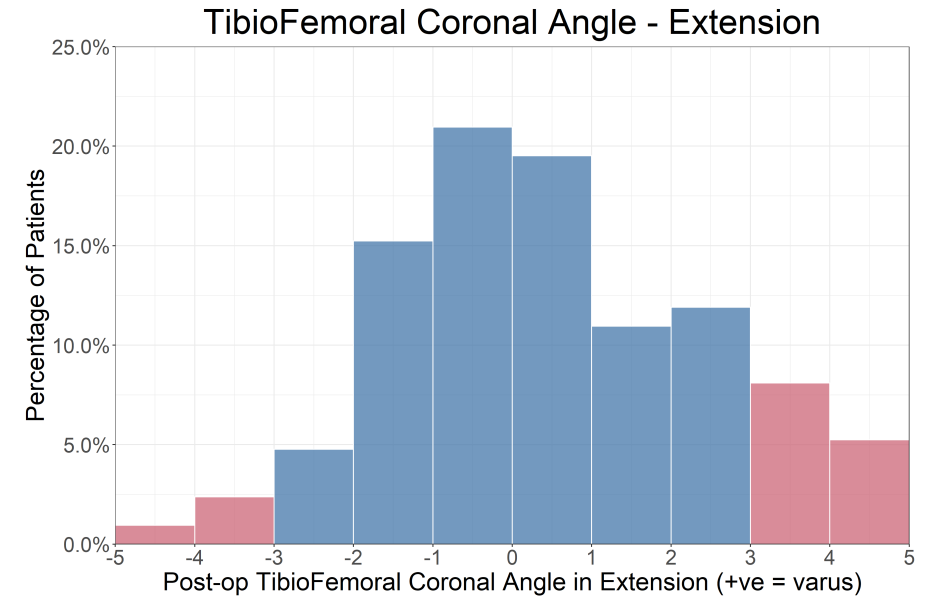
$\Delta 5.5, p = 0.006$



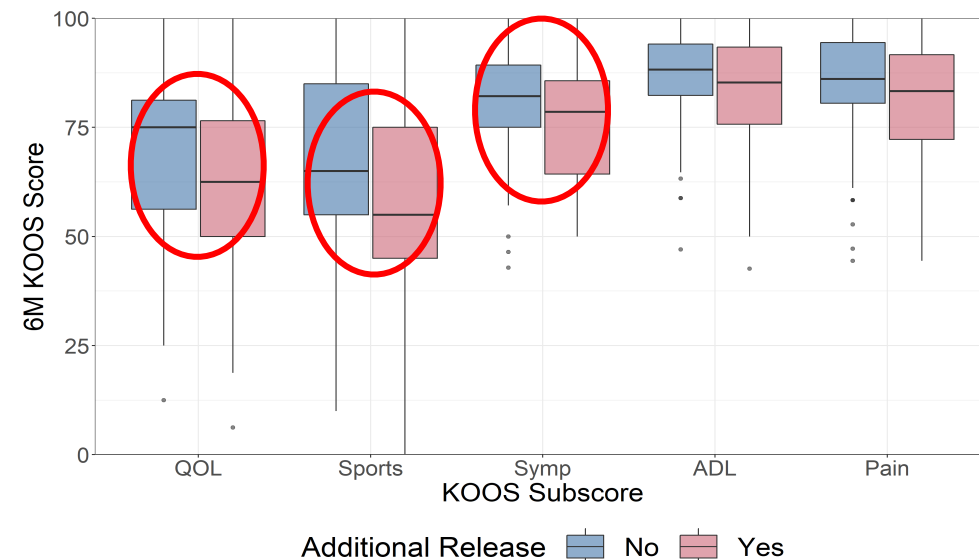
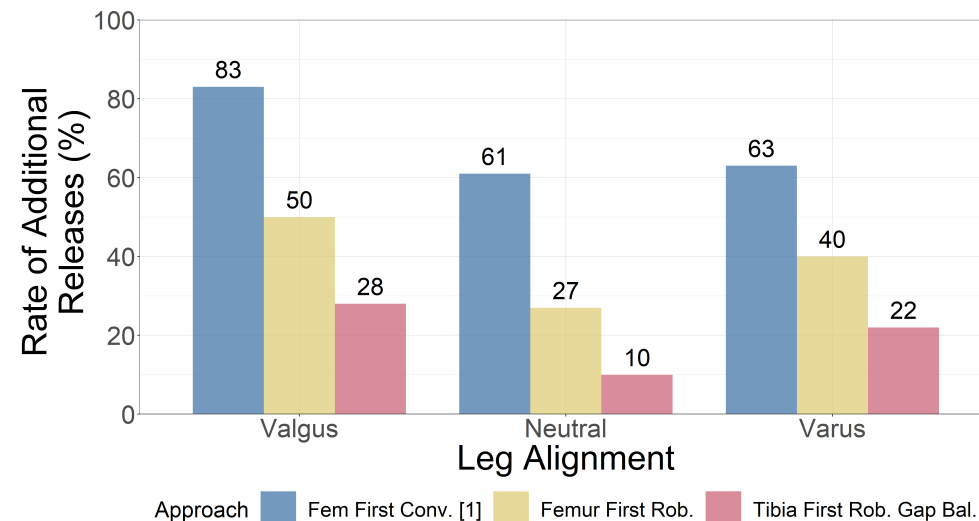
$\Delta 2.8, p = 0.012$



- Long leg alignment did **not** correlate with outcome
- Balance may have a greater effect on outcome than alignment
- What is the safe *limit* of non-neutral alignment?



- Predictive balance reduces the rate of soft tissue release across all deformities
- Knees with increased soft tissue releases reported poorer KOOS QOL, Sports and Symptoms scores
- When should a bone recut be performed *rather* than a release?



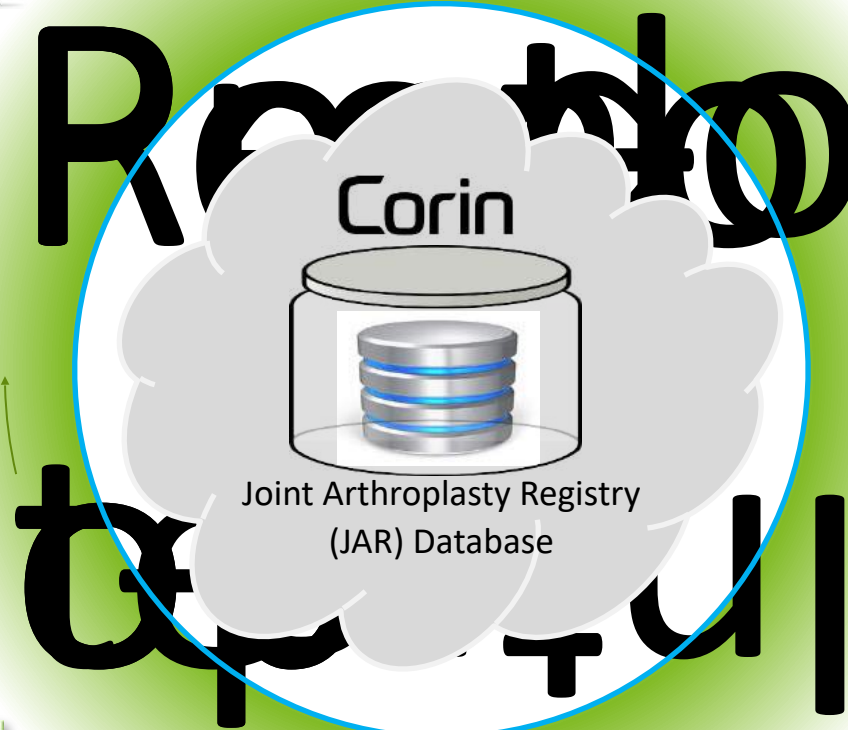
[1] Peters et al. JBJS 2013. n = 1216

## Part 3: Corin Joint Arthroplasty Registry

Patient Profiling  
Demographics  
Pre/Rehabilitation  
PROMs, Outcomes  
Activity Monitoring



Pre-op imaging/xray/CT/MRI  
Functional assessment  
Implant Planning



Joint Arthroplasty Registry  
(JAR) Database

Intra-op sensing/  
imaging  
Soft-tissue  
characterization  
Ligament balancing  
Implant Positioning



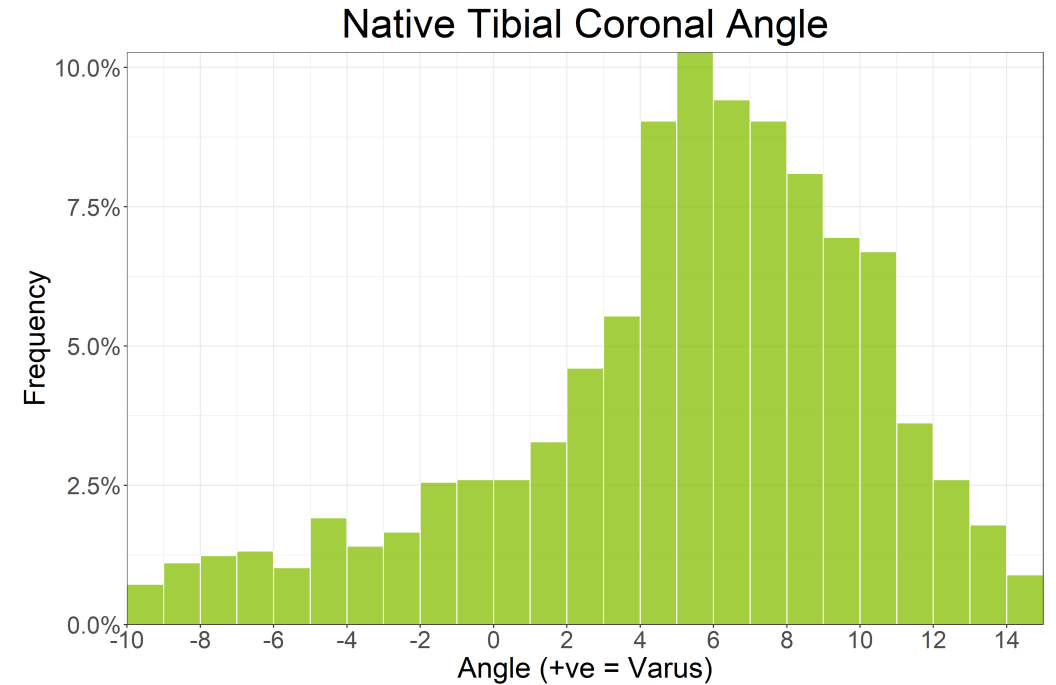
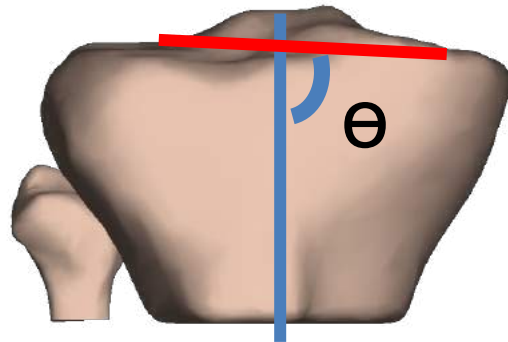
Post-op analysis  
Post-op imaging  
PMS  
National Registries



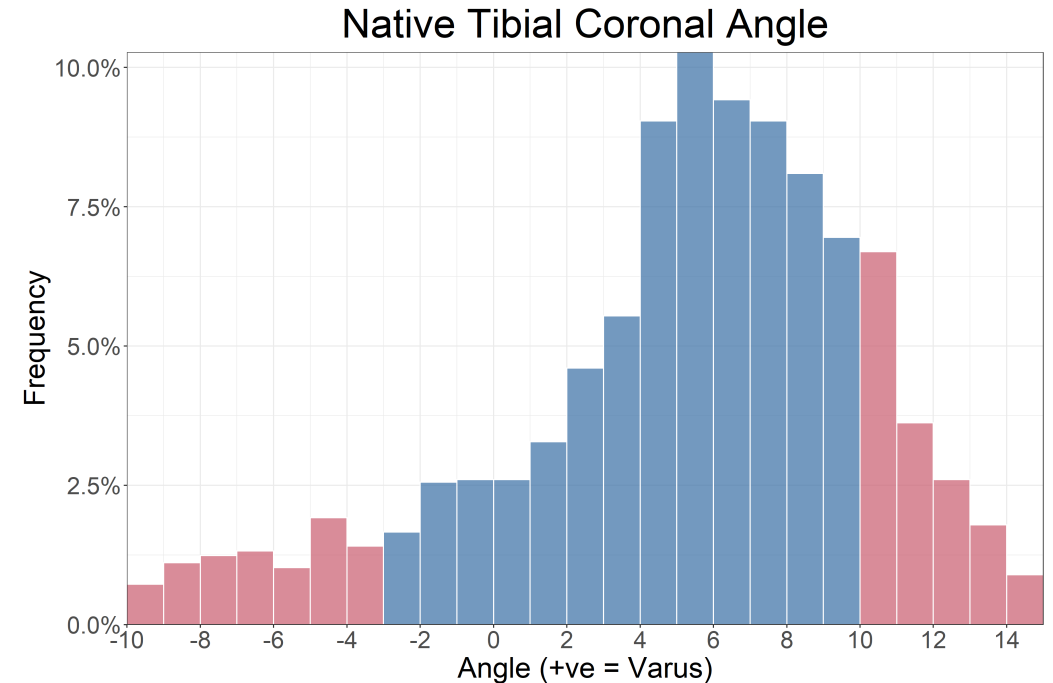
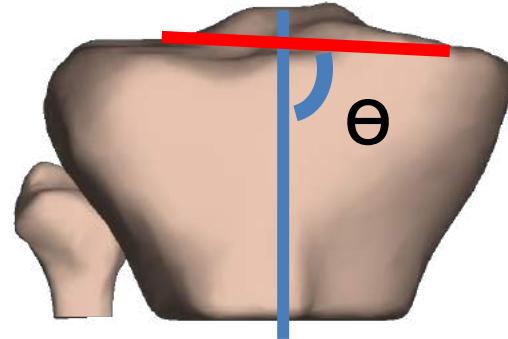
➤ Data collection through entire JA Journey

➤ Big data analysis for patient specific care

- 2447 OMNIBotics cases recorded in the registry
- Mean = 4.9° varus
- SD = 7.0°

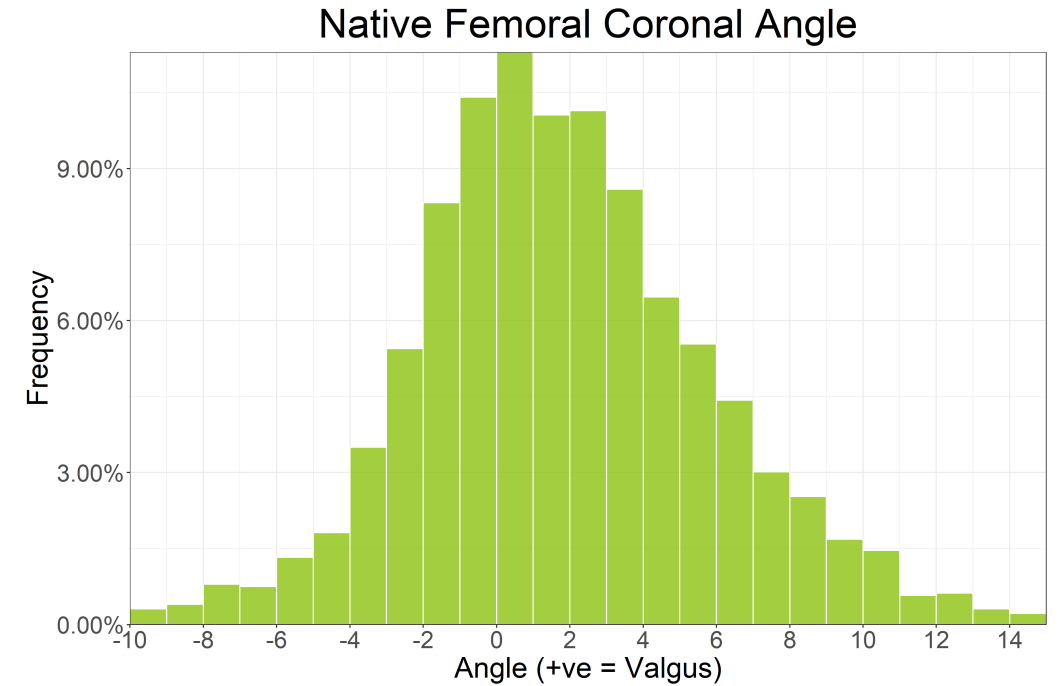
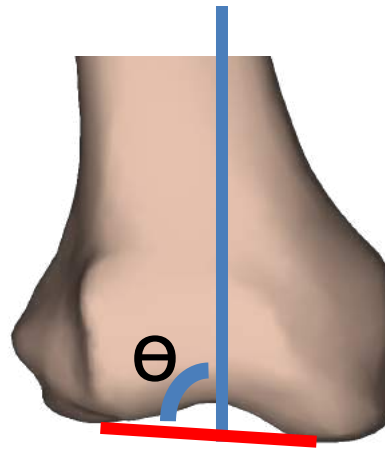


- 2447 OMNIBotics cases recorded in the registry
- Mean = 4.9° varus
- SD = 7.0°
- Inlier defined as between -3° – 10° varus
- 27% knees present outlier tibial anatomy

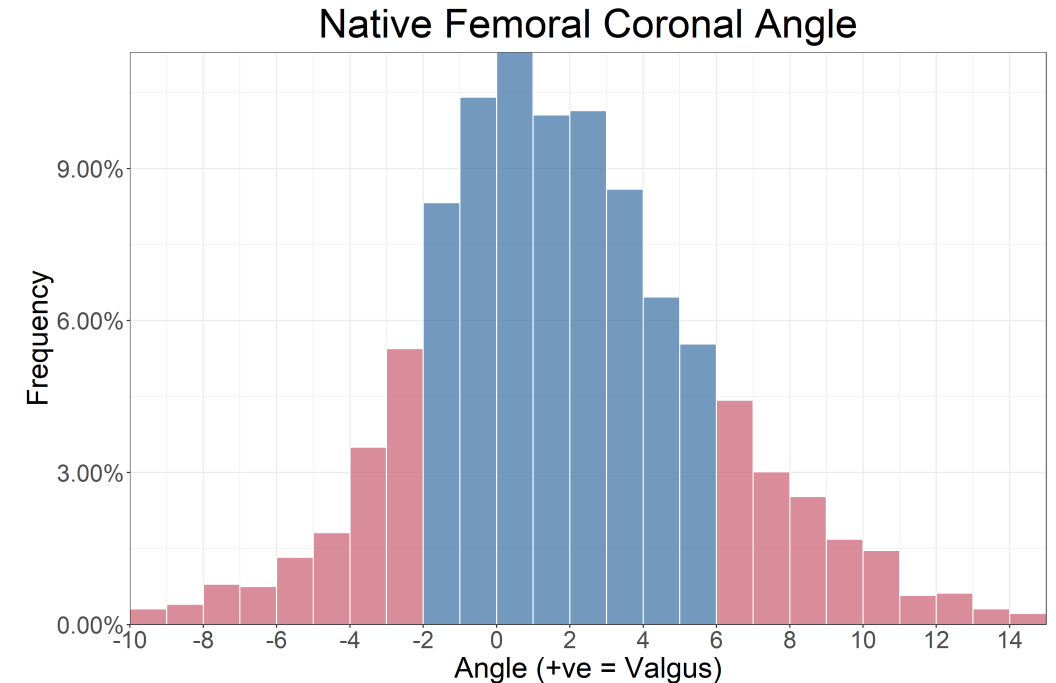
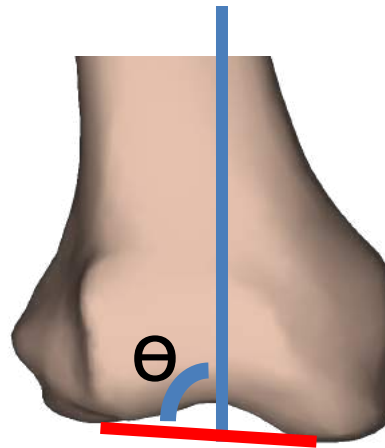




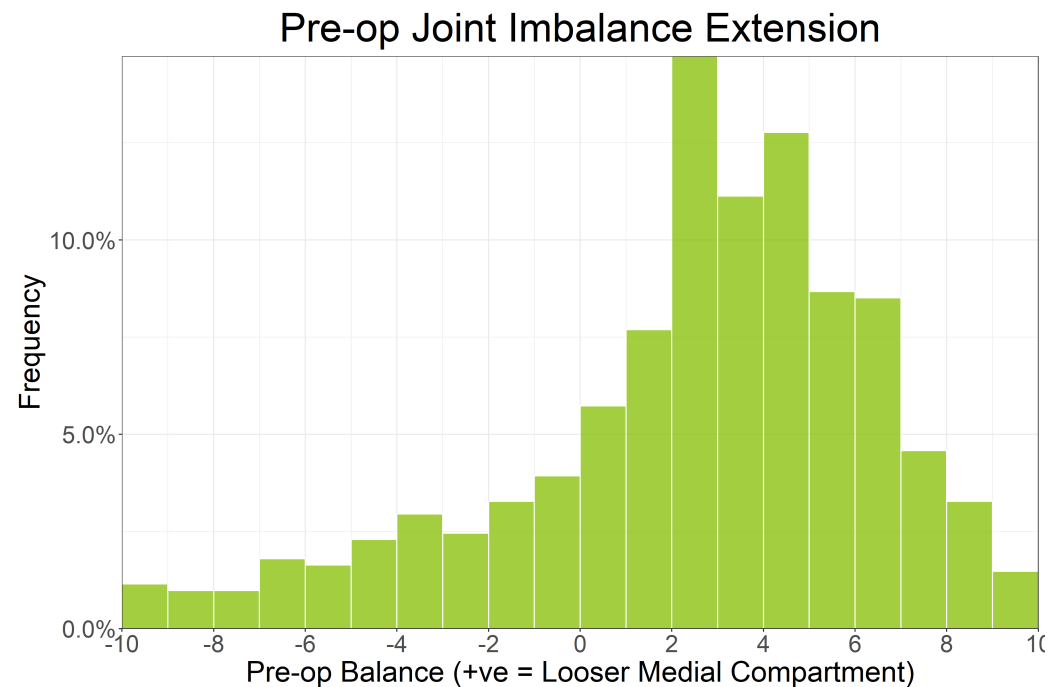
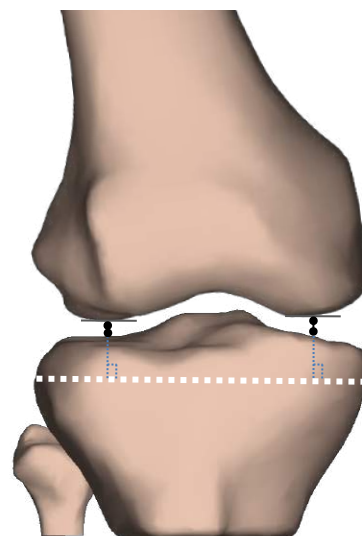
- 2447 OMNIBotics cases recorded in the registry
- Mean = 1.5° valgus
- SD = 5.5°



- 2447 OMNIBotics cases recorded in the registry
- Mean =  $1.5^\circ$  valgus
- SD =  $5.5^\circ$
- Inlier defined as between  $-2^\circ - 6^\circ$  valgus
- 34% knees present outlier femoral anatomy

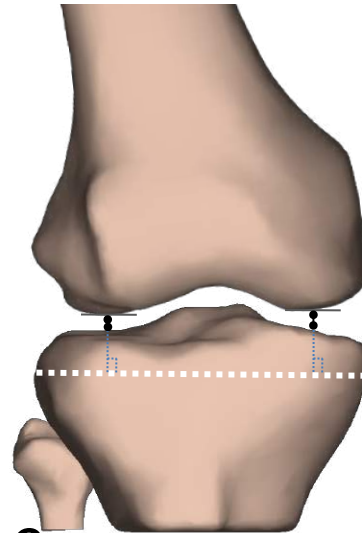


- 2447 OMNIBotics cases recorded in the registry
- Mean = 2.3 mm imbalance
- SD = 4.6 mm

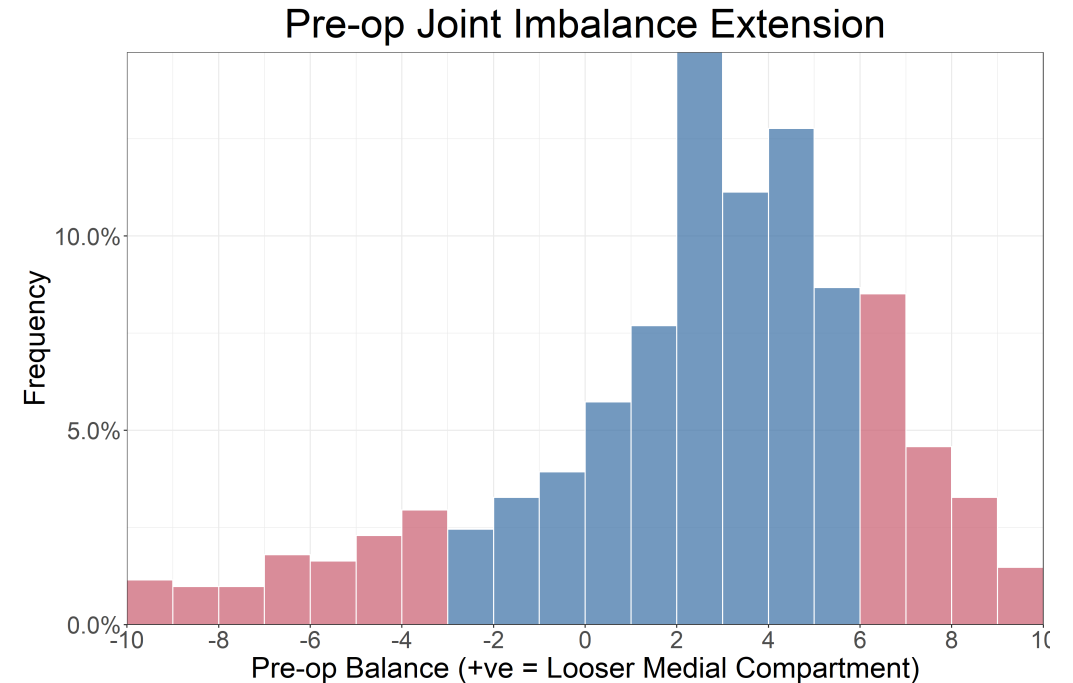


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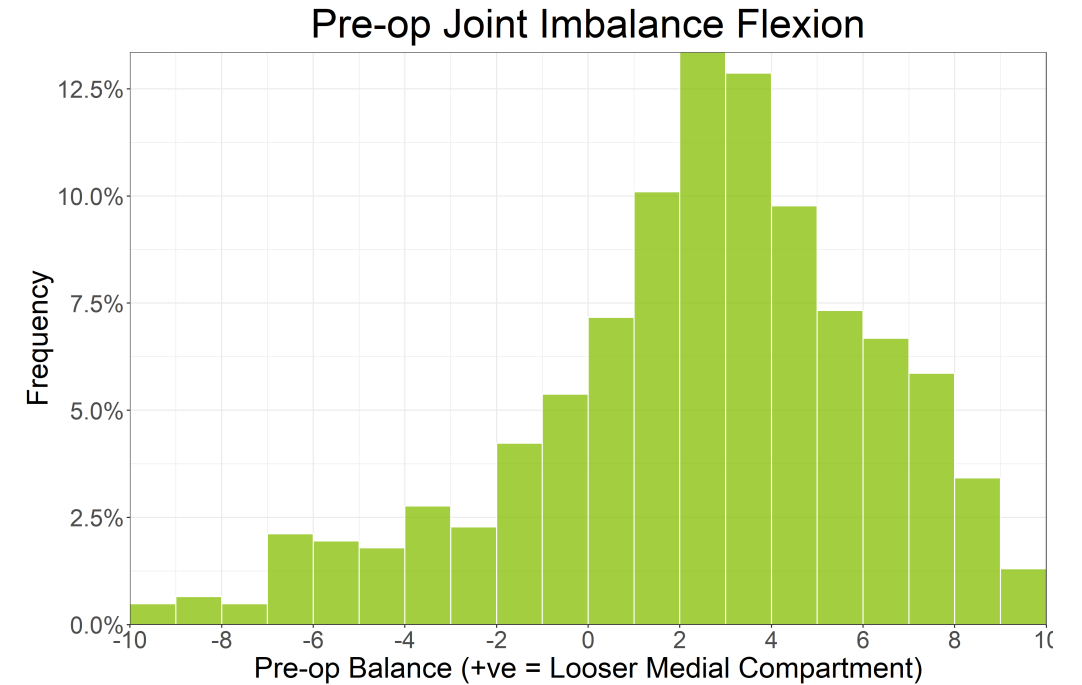
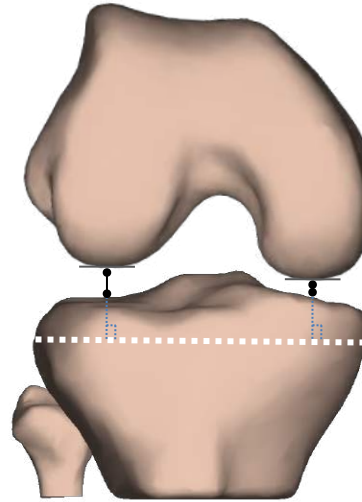
- Mean = 2.3 mm imbalance
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- Inlier defined as between -3 – 6 mm looser on medial side
- 32% of knees present with outlier joint balance in extension

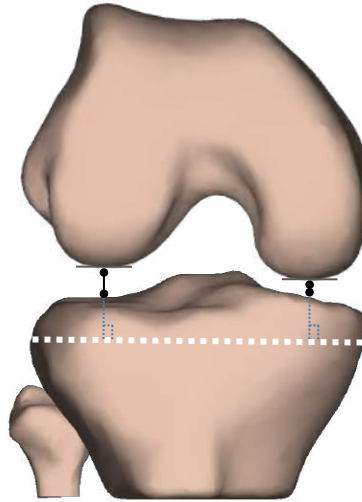


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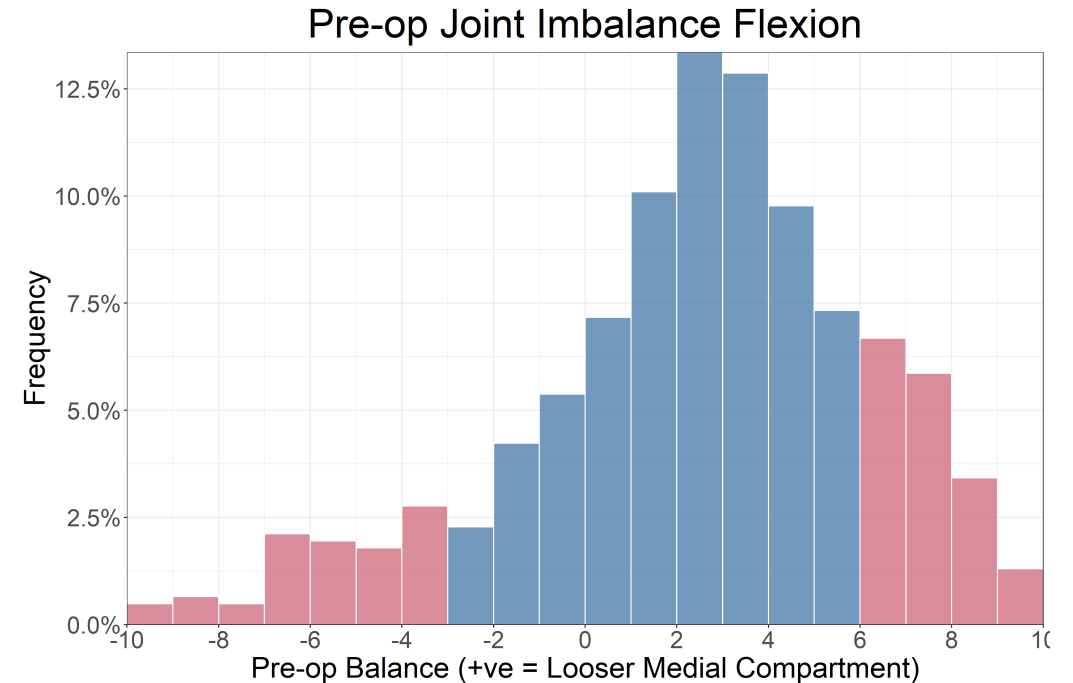


- 2447 OMNIBotics cases recorded in the registry

- Mean = 2.3 mm imbalance
- SD = 4.6 mm



- Inlier defined as between -3 – 6 mm looser on medial side
- 30% of knees present with outlier joint balance in extension





Variable	Frequency (%)
Tibial VV (-3° - 10°)	27
Femoral VV (-2° - 6°)	34
Pre-operative extension balance (-3 - 6 mm)	32
Pre-operative flexion balance (-3 - 6 mm)	30
Satisfies at least 1 criteria	<b>69</b>

So how do I do this efficiently in the OR?

## Part 4: Managing an Efficient OR with OmniBotics

# Background

- ▶ Education and training:
  - ▶ A.B., Harvard and Radcliffe Colleges
  - ▶ MD, Harvard Medical School
  - ▶ Internship and Residency: UMass Medical Center
  - ▶ Fellowship: Otto Aufranc fellowship in Adult Reconstruction, Boston, MA
- ▶ My evolution and history with respect to soft-tissue management in TKA

# My OMNIBotics Experience

- ▶ Began OMNIBotics in July of 2017
- ▶ BalanceBot in October of 2017
- ▶ Average 4-5 knees and 4-5 hips per day, in 2 rooms with dedicated staff
- ▶ Approximately 600+ cases per year

The beginnings: Why and how?

# Soft tissues

- ▶ Bony alignment and measured resection
- ▶ Manual guides, intramedullary versus extramedullary
- ▶ Femur first preparation
- ▶ Memorizing algorithms of releases to employ to balance gaps after resections already completely made



# Soft tissues

- ▶ Traditional methods versus navigation: a natural evolution
  - ▶ More accurate bony alignment
  - ▶ Sometimes, inaccurate bone cuts contributed to unequal gaps
  - ▶ With navigation, we became better at preparing the bone

# Soft tissues

- ▶ “Cheated navigation”
  - ▶ A game of sorts I used to play, to see if I could adjust the navigated parameters in such a way to “predict” a well balanced knee

I began to cut distal femur first, then the tibia, and use a tensioner in flexion

# Running an Efficient OR

- ▶ Running an Efficient OR with OMNIBotics
  - ▶ Multifactorial:
    - ▶ Preparation and planning (surgeon must oversee all steps)
    - ▶ Precise division of labor
      - ▶ Orthopedic specialty hospital
      - ▶ Dedicated scrub and RN staff, with cross-training
      - ▶ 2 scrub techs per case
      - ▶ 2 assistants per case (PA and CFA)
- ▶ Staff retention is critical

# Timeline of Operation

- ▶ 2 cases – 1 easy, 1 hard (this is the important bit)
- ▶ Dr Randall to communicate which cases

# Average Operation: 171 cases

- ▶ Average Total Tourniquet: 1 Hr 7 Min
- ▶ Average OMNIBotics time: 36 Min
  
- ▶ Landmarking: 4 mins
- ▶ Pre-operative kinematics: 1 min
- ▶ Tibia cut block position and planning: 4 min
- ▶ Tibia resection and validation: 2 min
- ▶ Pre-operative joint balance: 2 min
- ▶ Femoral planning: 3 min
- ▶ Robotic alignment and calibration: 3 min
- ▶ Femoral resections: 4 min
- ▶ Post-operative joint balance: 3 min
- ▶ Trialing, Cementing and Final Alignment: 10 min

# Conclusion: unique and adaptable

- ▶ The BalanceBot is the next step in navigation; building upon the navigated base of the tibial cut, with real-time assessment of the functional status of the soft tissues; enabling reacquisition of data after releases; and predictive mapping of total knee behavior



# Conclusion

- ▶ Conclusion
  - ▶ Good System
  - ▶ Great (improved) outcomes
  - ▶ How to combat “robots are inefficient” when presented with that argument.

- Every knee is different and presents its own unique challenges and compromises
- To provide robust patient specific guidelines to achieve optimal outcomes, more data is required:
  - Pre-operative disease
  - Activity
  - Psychological condition
  - Soft tissue characterization
  - Rehabilitation
- And all of this is needed on a large population!



- Integrated soft tissue balancing and robotics
  - **Real time gap and resection planning**
  - **Surgical execution of desired post-operative joint balance**
- Some clinical guidelines can be determined from clinical studies but more data is required
- Robotics (and data capture) can be efficient
- A wide variety of anatomy and soft tissue balance is present in the TKA population presenting a multitude of clinical challenges